

MPPT algorithm based on Multiple Linear Regression model for Solar PV systems



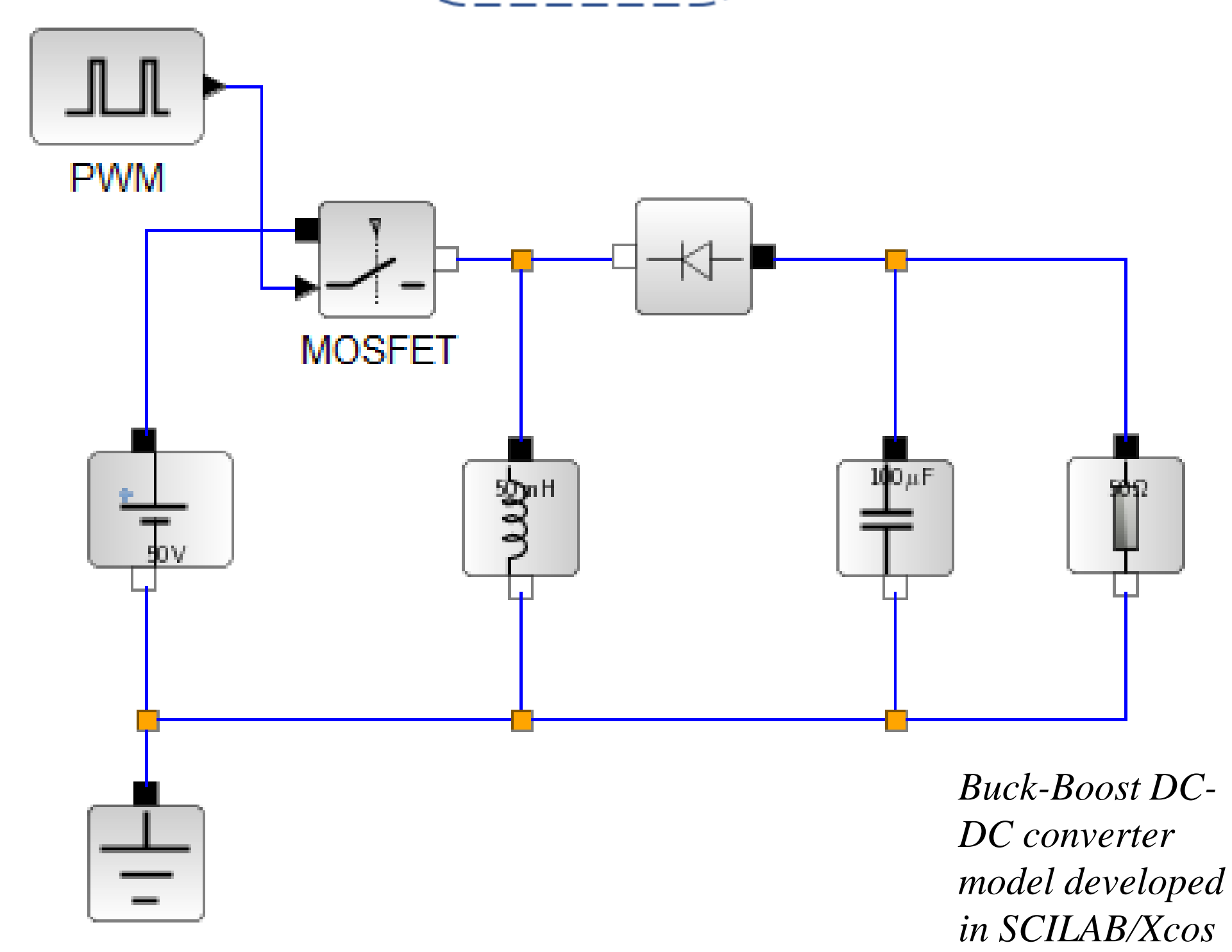
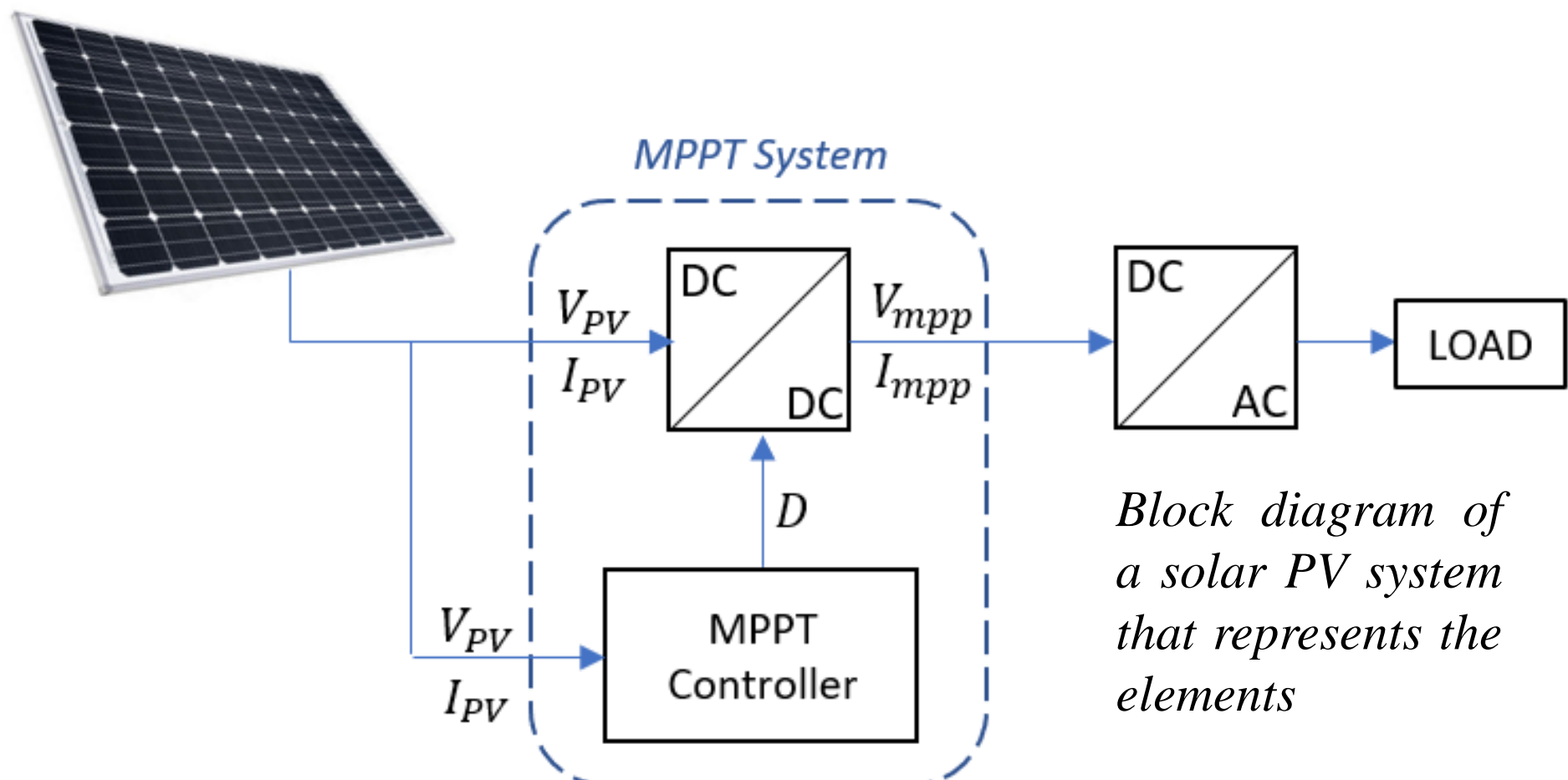
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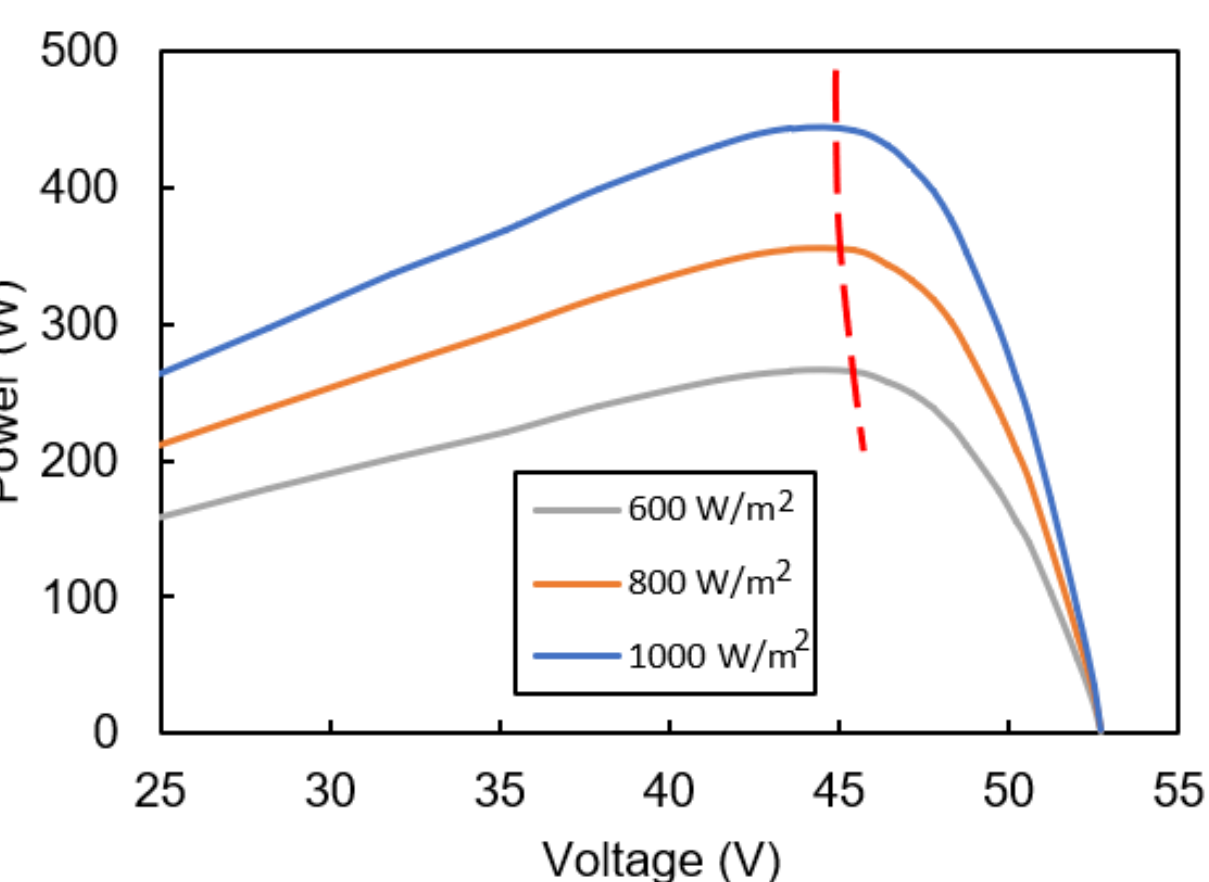
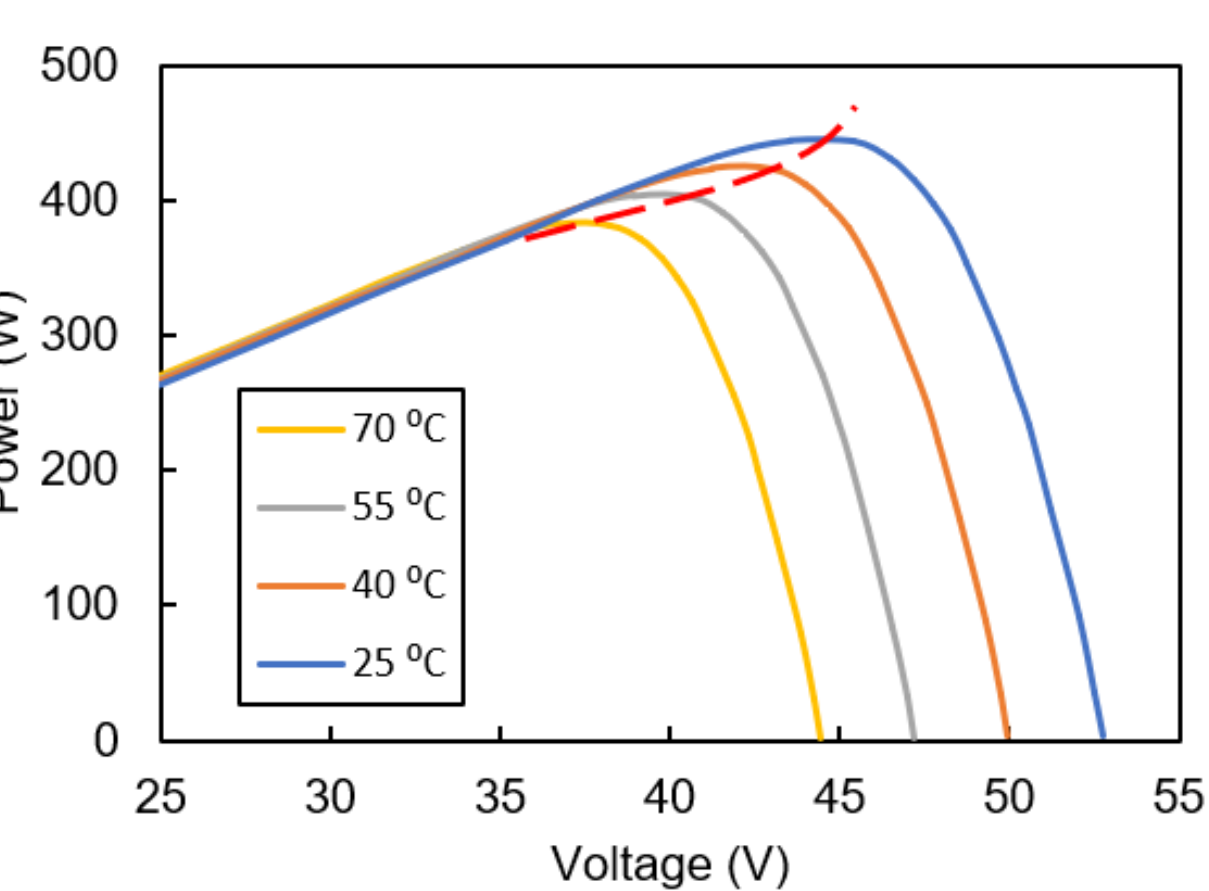
SUMMARY

This work presents a model to establish the optimal working point of photovoltaic panels to be used in installations sensitive to changes in environmental conditions, such as solar pumping, to obtain maximum power in any temperature and irradiance condition of the panels. The model reduces the response time of the system because it also has a control system implemented whose setpoint value is the one provided by the algorithm itself. This is possible with the help of external temperature and solar radiation sensors that provide these values in real time. The setpoint is the working voltage target for the panels (V_{mpp}), for which the system does not become unstable despite the oscillations allowed by the control system. The algorithm is based on a model that consists of a Multiple Linear Regression through which the entire P-V curve of any photovoltaic panel can be represented for any temperature and radiation.

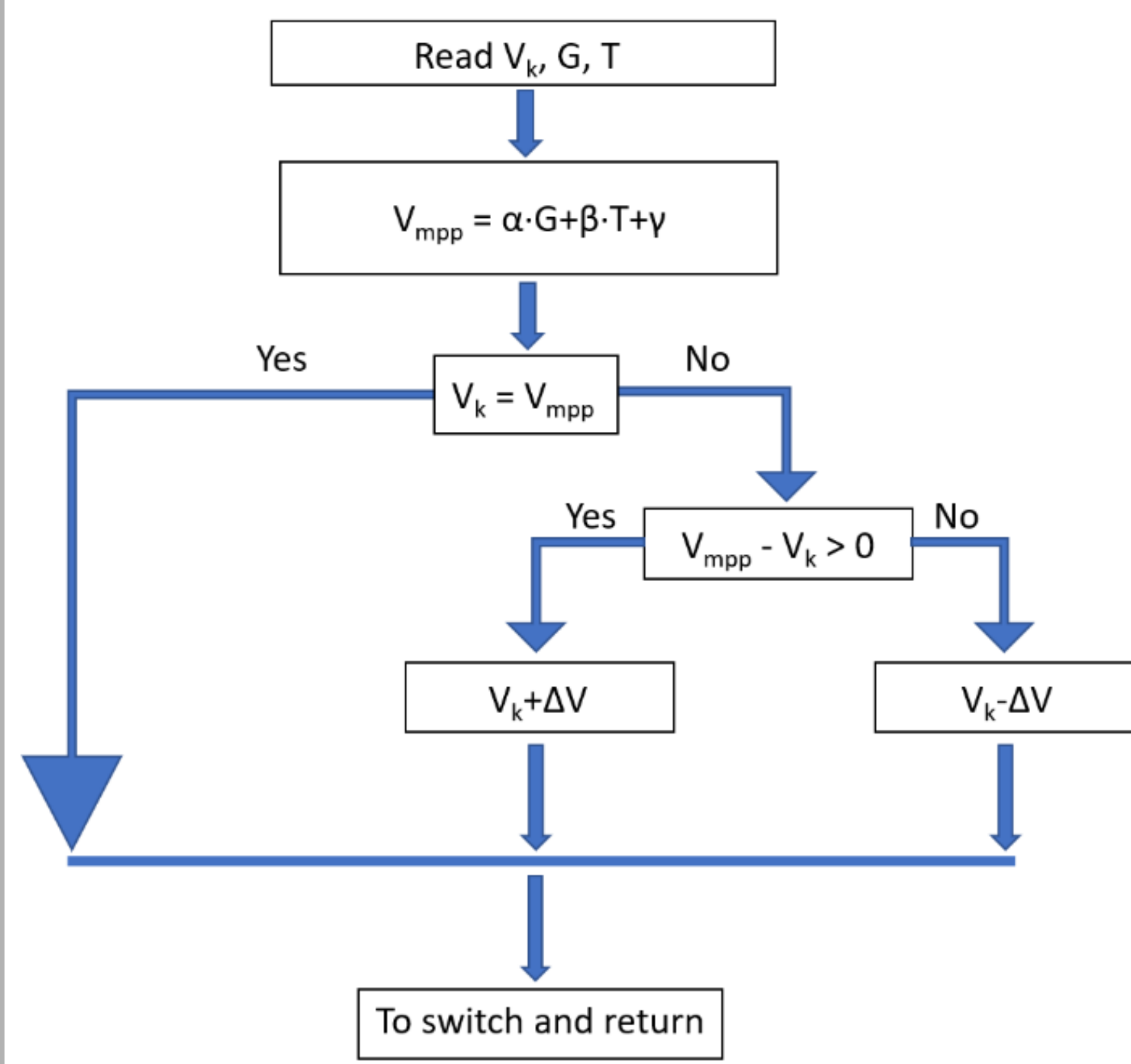
SOLAR PV SYSTEM DESCRIPTION



MULTIPLE LINEAL REGRESSION MODEL

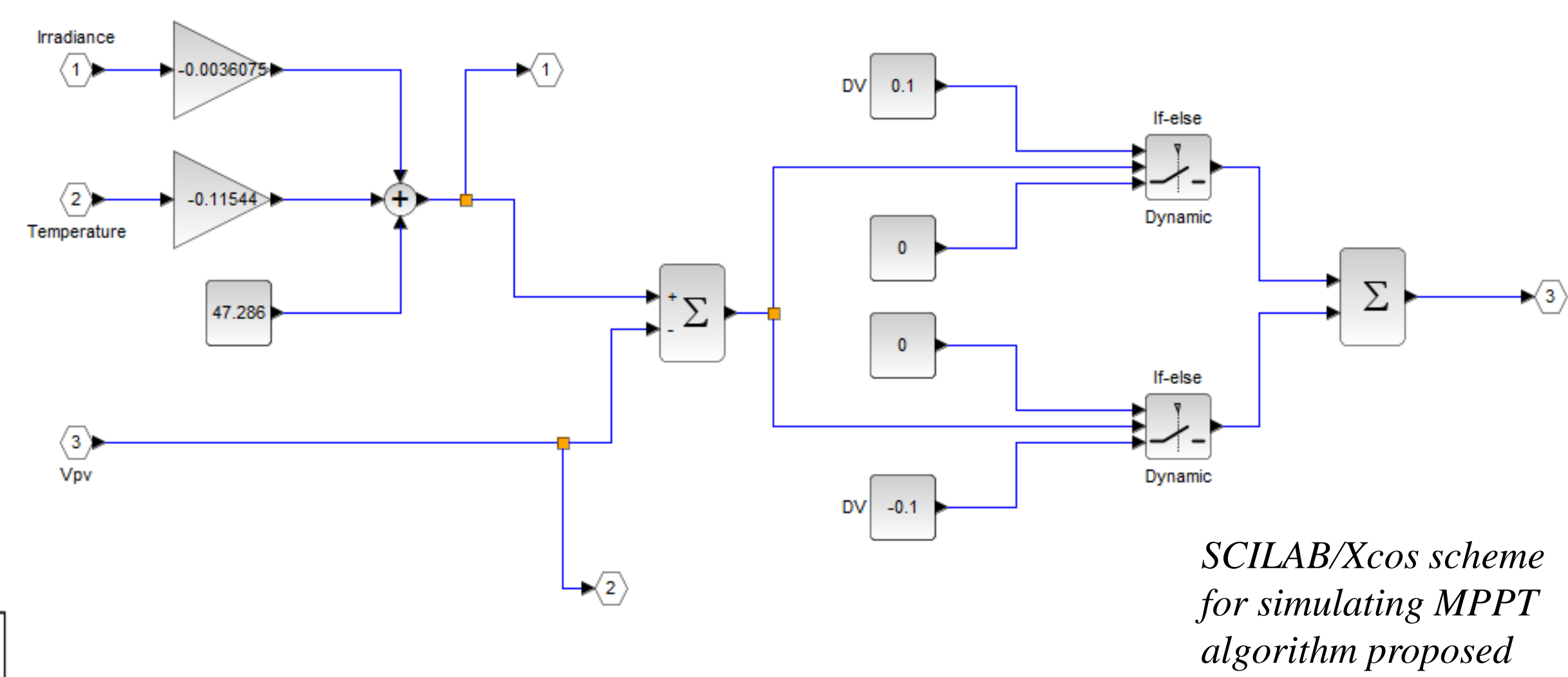


$$V_{mpp} = \alpha \cdot G + \beta \cdot T_{amb} + \gamma$$



Flowchart of the MPPT algorithm proposed

ALGORITHM

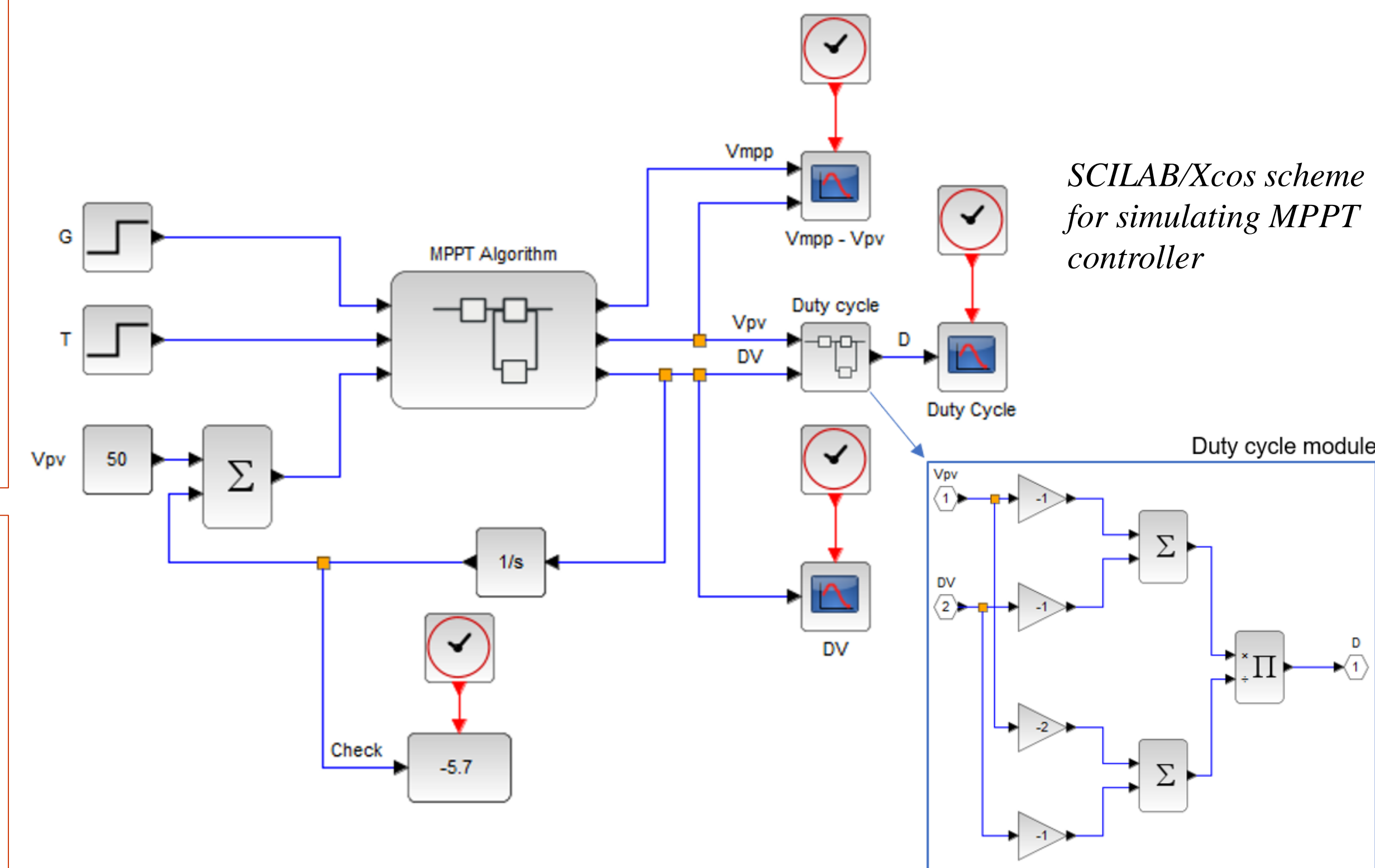


The equation that allows us obtaining the duty cycle ratio D of the Buck-Boost DC-DC converter as function of step size ΔV is:

$$V_{out} = \frac{D}{1-D} \cdot V_{in} \quad \rightarrow \quad D = \frac{V_{in} \pm \Delta V}{2V_{in} \pm \Delta V}$$

SIMULATIONS

MAGNITUDE	RANGE
Ambient Temperature	25°C-50°C
Irradiance	600 – 1000 W/m ²



The equation that allows us to obtain the step size ΔV as a function of the duty cycle ratio D is the following transfer function of the DC-DC converter. With this equation, a PID could easily be designed to reduce oscillations and reach the target voltage faster.

$$\frac{V_{out}}{V_{in}} = \frac{D(D-1)}{LCs^2 + \frac{L}{C}s + (1-D)^2}$$

